

Probabilistic models

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Maximum Likelihood Estimation

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Slides based on Lecture 06b from David Rosenberg's course materials
(<https://github.com/davidrosenberg/mlcourse>)

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The Data: Assumptions So Far in this Course

- Our usual setup is that (x, y) pairs are drawn **i.i.d. from** $\mathcal{P}_{\mathcal{X} \times \mathcal{Y}}$.
- So far ridge/lasso/ regression, optimization, SVMs, and kernel methods are applicable for arbitrary training data sets $\mathcal{D} : (x_1, y_1), \dots, (x_n, y_n) \in \mathcal{X} \times \mathcal{Y}$.
 - i.e. \mathcal{D} could be created by hand, by an adversary, or randomly.
- How have we used this assumption so far?
 - motivates empirical risk minimization
 - ties test performance to performance on new data when deployed
- We rely on the i.i.d. $\mathcal{P}_{\mathcal{X} \times \mathcal{Y}}$ assumption when it comes to **generalization** only.

Probabilistic Models: Use Assumptions on the Data for Learning

- Observations y are drawn i.i.d. from a distribution \mathcal{P}_y
→ **Maximum likelihood estimation** (First topic of week 6)
- Model how y depends on x
→ **Conditional probability models** $p(y|x)$ (Second topic of week 6)
- Incorporate prior knowledge and estimate uncertainty on the prediction
→ **Bayesian approaches** (Topic of week 7)

Maximum Likelihood Estimation: Contents

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Estimating a Probability Distribution: Setting

For the moment we only assume that we have one variable y .

- Let $p(y)$ represent a probability distribution on \mathcal{Y} .
- $p(y)$ is **unknown** and we want to **estimate** it.
- Assume that $p(y)$ is either a
 - probability density function on a continuous space \mathcal{Y} , or a
 - probability mass function on a discrete space \mathcal{Y} .
- Typical \mathcal{Y} 's:
 - $\mathcal{Y} = \mathbf{R}$; $\mathcal{Y} = \mathbf{R}^d$ [typical continuous distributions]
 - $\mathcal{Y} = \{-1, 1\}$ [e.g. binary classification]
 - $\mathcal{Y} = \{0, 1, 2, \dots, K\}$ [e.g. multiclass problem]
 - $\mathcal{Y} = \{0, 1, 2, 3, 4, \dots\}$ [unbounded counts]

Evaluating a Probability Distribution Estimate

- Before we talk about estimation, let's talk about evaluation.
- Somebody gives us an estimate of the probability distribution

$$\hat{p}(y).$$

- How can we evaluate how good it is?
- We want $\hat{p}(y)$ to be descriptive of **future** data.

Likelihood of a Predicted Distribution

- Suppose we have

$\mathcal{D} = (y_1, \dots, y_n)$ sampled i.i.d. from true distribution $p(y)$.

- Then the **likelihood** of \hat{p} for the data \mathcal{D} is defined to be

$$\hat{p}(\mathcal{D}) = \prod_{i=1}^n \hat{p}(y_i).$$

The probability of observing \mathcal{D} under the estimate \hat{p} .

How are we going to construct an estimate of $\hat{p}(y)$?

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Definition

A **parametric model** is a set of probability distributions indexed by a parameter $\theta \in \Theta$. We denote this as

$$\{p(y; \theta) \mid \theta \in \Theta\},$$

where θ is the **parameter** and Θ is the **parameter space**.

- Below we'll give some examples of common parametric models.
 - But it's worth doing research to find a parametric model most appropriate for your data.
- We'll sometimes say **family of distributions** for a probability model.

Poisson Family

- Support $\mathcal{Y} = \{0, 1, 2, 3, \dots\}$.
- Parameter space: $\{\lambda \in \mathbf{R} \mid \lambda > 0\}$
- Probability mass function on $k \in \mathcal{Y}$:

$$p(k; \lambda) = \lambda^k e^{-\lambda} / (k!)$$

- Examples: Number of random i.i.d. events in a given time/over an interval
 - Radioactive decay of atoms over a year
 - Number of taxi cab pickups at Penn Station in an evening

- Support $\mathcal{Y} = (0, 1)$. [The unit interval.]
- Parameter space: $\{\theta = (\alpha, \beta) \mid \alpha, \beta > 0\}$
- Probability density function on $y \in \mathcal{Y}$:

$$p(y; a, b) = \frac{y^{\alpha-1} (1-y)^{\beta-1}}{B(\alpha, \beta)}$$

- Examples: Spending of a resource over a interval.
 - Project management

Gaussian Family

- Support $\mathcal{Y} \in \mathbf{R}$.
- Parameter space: $\{\theta = (\mu, \sigma^2) \mid \mu \in \mathbf{R}, \sigma^2 > 0\}$
- Probability density function on $y \in \mathcal{Y}$:

$$p(y; \mu, \sigma) = \frac{1}{\sqrt{2\pi\sigma}} e^{-(y-\sigma)^2/2\sigma^2}.$$

- Also named "normal" distribution, noted $\mathcal{N}(\mu, \sigma^2)$
- Examples: sum of i.i.d random variables (Central limit theorem)
 - Cumulated gain from random independent coin flips

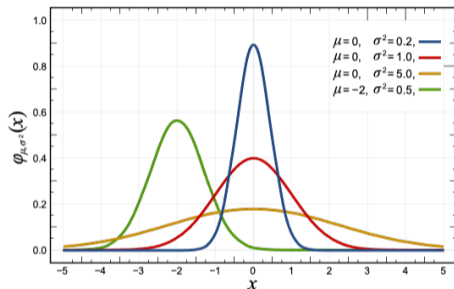


Figure from Wikipedia https://en.wikipedia.org/wiki/Gaussian_function.

Multivariate Distributions

- Above we only cited examples of univariate distributions
- Sometimes we need multivariate distributions $p(y; \theta)$ for $y = (y_1, \dots, y_d) \in \mathbf{R}^d$:
 - If y_i s are independent $p(y; \theta) = \prod_{i=1}^d p(y_i; \theta_i)$
 - If there are correlations, we have to treat the problem in dimension d .

- Example:
Multivariate Gaussian Distribution

- In 2d: $y \in \mathbf{R}^2$, $p(y; \theta) = \mathcal{N}(\mu; \Sigma)$
- Parameters:
 - Mean vector $\mu \in \mathbf{R}^2$
 - Covariance matrix $\Sigma \in \mathbf{R}^{2 \times 2}$

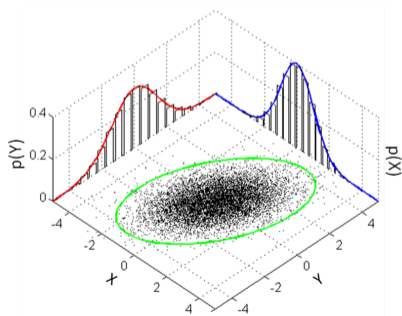


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Likelihood in a Parametric Model

Suppose we have a parametric model $\{p(y; \theta) \mid \theta \in \Theta\}$ and a sample $\mathcal{D} = (y_1, \dots, y_n)$.

- The **likelihood** of parameter estimate $\hat{\theta} \in \Theta$ for sample \mathcal{D} is

$$p(\mathcal{D}; \hat{\theta}) = \prod_{i=1}^n p(y_i; \hat{\theta}).$$

- In practice, we prefer to work with the **log-likelihood**. Same maximizer, but

$$\log p(\mathcal{D}; \hat{\theta}) = \sum_{i=1}^n \log p(y_i; \hat{\theta}),$$

and sums are easier to work with than products.

Maximum Likelihood Estimation

- Suppose $\mathcal{D} = (y_1, \dots, y_n)$ is an i.i.d. sample from some distribution.

Definition

A **maximum likelihood estimator (MLE)** for θ in the model $\{p(y; \theta) \mid \theta \in \Theta\}$ is

$$\begin{aligned}\hat{\theta} &\in \arg \max_{\theta \in \Theta} \log p(\mathcal{D}, \hat{\theta}) \\ &= \arg \max_{\theta \in \Theta} \sum_{i=1}^n \log p(y_i; \theta).\end{aligned}$$

Maximum Likelihood Estimation

- Finding the MLE is an **optimization problem**.
- For some model families, calculus gives a closed form for the MLE.
- Can also use numerical methods we know (e.g. SGD).

- In certain situations, the MLE may not exist.
- But there is usually a good reason for this.
- e.g. Gaussian family $\{\mathcal{N}(\mu, \sigma^2) \mid \mu \in \mathbf{R}, \sigma^2 > 0\}$
- We have a single observation y .
- Is there an MLE?
- Taking $\mu = y$ and $\sigma^2 \rightarrow 0$ drives likelihood to infinity.
- MLE doesn't exist.

Example: MLE for Poisson

- Observed counts $\mathcal{D} = (k_1, \dots, k_n)$ for taxi cab pickups over n weeks.
 - k_i is number of pickups at Penn Station Mon, 7-8pm, for week i .
- We want to fit a Poisson distribution to this data.
- The Poisson log-likelihood for a single count is

$$\begin{aligned}\log [p(k; \lambda)] &= \log \left[\frac{\lambda^k e^{-\lambda}}{k!} \right] \\ &= k \log \lambda - \lambda - \log(k!)\end{aligned}$$

- The full log-likelihood is

$$\log p(\mathcal{D}, \lambda) = \sum_{i=1}^n [k_i \log \lambda - \lambda - \log(k_i!)].$$

Example: MLE for Poisson

- The full log-likelihood is

$$\log p(\mathcal{D}, \lambda) = \sum_{i=1}^n [k_i \log \lambda - \lambda - \log(k_i!)]$$

- First order condition gives

$$\begin{aligned} 0 = \frac{\partial}{\partial \lambda} [\log p(\mathcal{D}, \lambda)] &= \sum_{i=1}^n \left[\frac{k_i}{\lambda} - 1 \right] \\ \implies \lambda &= \frac{1}{n} \sum_{i=1}^n k_i \end{aligned}$$

- So MLE $\hat{\lambda}$ is just the mean of the counts.

Estimating Distributions, Overfitting, and Hypothesis Spaces

- Just as in classification and regression, MLE can overfit!
- Example Probability Models: Penn Station, Mon-Fri 7-8pm
 - $\mathcal{F} = \{\text{Poisson distributions}\}$.
 - $\mathcal{F} = \{\text{Negative binomial distributions}\}$.
- How to judge which model works the best?
- Choose the model with the **highest likelihood on validation set**.
 - Test Set Log Likelihood for Penn Station, Mon-Fri 7-8pm

Method	Test Log-Likelihood
Poisson	-392.16
Negative Binomial	-188.67