Discussion

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- Our data is typically not linearly separable.
- But we like to work with linear models.
- Adding features (going to high-dimensional space) allow us to use linear models for complex data.
- Kernels allow us to think about similarities rather than feature engineering.

Two perspectives on kernels

- Given a feature map $\phi: \mathfrak{X} \to \mathfrak{H}$, we can define a kernel function $k(x, x') = \langle \phi(x), \phi(x') \rangle_{\mathfrak{H}}$.
- Given a PD kernel $k: \mathfrak{X} \times \mathfrak{X} \to \mathsf{R}$, there exists a corresponding feature map.
 - Note that the kernel does not uniquely define the feature map.
- In practice we typically only work with the kernel function. 7 R K H C / R K k(x, -)

X -> H eatare map

RBF Kernel

RBF Basis

Input space $\mathfrak{X} = \mathsf{R}^d$

$$k(x,x') = \exp\left(-\frac{\|x-x'\|^2}{2\sigma^2}\right),$$

where σ^2 is known as the bandwidth parameter.

- Suppose we have 6 training examples: $x_i \in \{-6, -4, -3, 0, 2, 4\}$.
- If representer theorem applies, then



RBF Predictions





• Predictions of the form $f(x) = \sum_{i=1}^{6} \alpha_i k(x_i, x)$:



• When kernelizing with RBF kernel, prediction functions always look this way (whether we get *w* from SVM, ridge regression).

Effect of the bandwidth

How does the fitted function change when we vary the bandwidth parameter?

https://mccormickml.com/2014/02/26/kernel-regression/ He He (CDS, NYU) DS-GA 1003

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Feature map of RBF kernel

What feature map corresponds to the RBF kernel? Consider the 1D case ($x \in R$) where $\sigma = 1$:



Based on https://www.cs.ubc.ca/~schmidtm/Courses/540-W19/L12.5.pdf

Kernel Methods

- A method can be kernelized if both training and inference only need inner produc in the feature space.
- Representer theorem says that all norm-regularized linear models can be kernelized.
 - Although we might be in a high dimensional space, w lies in the subspace spanned by $\phi(x_i)$.
 - Dimension of the subspace grows with the dataset size.
- Many other algorithms can be kernelized.

Kernelized perceptron

 $w^* = \sum_i d_i X_i$ Prediction : W·X=Zidiki·X • Initialize $w \leftarrow 0$ • While not converged = Siai (NUN) • For $(x_i, v_i) \in \mathcal{D}$ = k. d • If $y_i w^T x_i < 0 \longrightarrow y_i k^T \alpha < 0$ • Update $w \leftarrow w + y_i x_i \longrightarrow d_i \leftarrow d_i + y_i$ $\sum_{i \in \mathcal{X}_i} \chi_i \in \sum_{i \in \mathcal{X}_i} \chi_i + y_i \chi_i$

- Distance-based methods depending on ||x-x'||² < x-x', x-x'>
 k-means clustering = < x, x> 2 < x, x'> + < x', x'>

 - *k*-nearest neighbors
- Eigenvalue methods: can show that eigenvector is in the span of data
 - Principal component analysis
 - Spectral clustering

Kernel SVM vs ridge

• For both kernel SVM and ridge regression, we make predictions by

$$\hat{f}(x) = k_x^T \alpha^* = \sum_{i=1}^n \alpha_i^* k(x_i, x)$$

- $\bullet\,$ For SVM, we have sparsity in α^* from complementary slackness.
- For ridge, we need to access all training examples.
- For large-scale dataset, we may not be able to store/compute the kernel matrix.
 - Large-scale kernel machines (e.g. Random Features for Large-Scale Kernel Machines)