

Multiclass & Structured Prediction

DS-GA 1003 Machine Learning

CDS, NYU

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Multiclass Hypothesis Space: Reframed

- **General [Discrete] Output Space:** \mathcal{Y}
- **Base Hypothesis Space:** $\mathcal{H} = \{h: \mathcal{X} \times \mathcal{Y} \rightarrow \mathbb{R}\}$
 - $h(x, y)$ gives **compatibility score** between input x and output y
- **Multiclass Hypothesis Space**

$$\mathcal{F} = \left\{ x \mapsto \arg \max_{y \in \mathcal{Y}} h(x, y) \mid h \in \mathcal{H} \right\}$$

- Final prediction function is an $f \in \mathcal{F}$.
- For each $f \in \mathcal{F}$ there is an underlying compatibility score function $h \in \mathcal{H}$.

Part-of-speech (POS) Tagging

- Given a sentence, give a part of speech tag for each word:

x	$\underbrace{[\text{START}]}_{x_0}$	$\underbrace{\text{He}}_{x_1}$	$\underbrace{\text{eats}}_{x_2}$	$\underbrace{\text{apples}}_{x_3}$
y	$\underbrace{[\text{START}]}_{y_0}$	$\underbrace{\text{Pronoun}}_{y_1}$	$\underbrace{\text{Verb}}_{y_2}$	$\underbrace{\text{Noun}}_{y_3}$

- $\mathcal{V} = \{\text{all English words}\} \cup \{[\text{START}], ", ."]\}$
- $\mathcal{P} = \{\text{START, Pronoun, Verb, Noun, Adjective}\}$
- $\mathcal{X} = \mathcal{V}^n, n = 1, 2, 3, \dots$ [Word sequences of any length]
- $\mathcal{Y} = \mathcal{P}^n, n = 1, 2, 3, \dots$ [Part of speech sequence of any length]

Structured Prediction

- A **structured prediction** problem is a multiclass problem in which \mathcal{Y} is very large, but has (or we assume it has) a certain structure.
- For POS tagging, \mathcal{Y} grows exponentially in the length of the sentence.
- Typical **structure** assumption: The POS labels form a Markov chain.
 - i.e. $y_{n+1} \mid y_n, y_{n-1}, \dots, y_0$ is the same as $y_{n+1} \mid y_n$.

Local Feature Functions: Type 1

- A “type 1” **local feature** only depends on
 - the label at a single position, say y_i (label of the i th word) and
 - x at any position
- Example:

$$\phi_1(i, x, y_i) = 1(x_i = \text{runs})1(y_i = \text{Verb})$$

$$\phi_2(i, x, y_i) = 1(x_i = \text{runs})1(y_i = \text{Noun})$$

$$\phi_3(i, x, y_i) = 1(x_{i-1} = \text{He})1(x_i = \text{runs})1(y_i = \text{Verb})$$

Local Feature Functions: Type 2

- A “type 2” **local feature** only depends on
 - the labels at 2 consecutive positions: y_{i-1} and y_i
 - x at any position
- Example:

$$\theta_1(i, x, y_{i-1}, y_i) = 1(y_{i-1} = \text{Pronoun})1(y_i = \text{Verb})$$

$$\theta_2(i, x, y_{i-1}, y_i) = 1(y_{i-1} = \text{Pronoun})1(y_i = \text{Noun})$$

Local Feature Vector and Compatibility Score

- At each position i in sequence, define the **local feature vector**:

$$\Psi_i(x, y_{i-1}, y_i) = (\phi_1(i, x, y_i), \phi_2(i, x, y_i), \dots, \theta_1(i, x, y_{i-1}, y_i), \theta_2(i, x, y_{i-1}, y_i), \dots)$$

- **Local compatibility score** for (x, y) at position i is $\langle w, \Psi_i(x, y_{i-1}, y_i) \rangle$.

Sequence Compatibility Score

- The **compatibility score** for the pair of sequences (x, y) is the sum of the local compatibility scores:

$$\begin{aligned} & \sum_i \langle w, \Psi_i(x, y_{i-1}, y_i) \rangle \\ &= \left\langle w, \sum_i \Psi_i(x, y_{i-1}, y_i) \right\rangle \\ &= \langle w, \Psi(x, y) \rangle, \end{aligned}$$

where we define the sequence feature vector by

$$\Psi(x, y) = \sum_i \Psi_i(x, y_{i-1}, y_i).$$

- So we see this is a special case of linear multiclass prediction.

Sequence Target Loss

- How do we assess the loss for prediction sequence y' for example (x, y) ?
- **Hamming loss** is common:

$$\Delta(y, y') = \frac{1}{|y|} \sum_{i=1}^{|y|} 1(y_i \neq y'_i)$$

- Could generalize this as

$$\Delta(y, y') = \frac{1}{|y|} \sum_{i=1}^{|y|} \delta(y_i, y'_i)$$

What remains to be done?

- To compute predictions, we need to find

$$\arg \max_{y \in \mathcal{Y}} \langle w, \Psi(x, y) \rangle.$$

- This is straightforward for $|\mathcal{Y}|$ small.
- Now $|\mathcal{Y}|$ is exponentially large.
- Because Ψ breaks down into local functions only depending on 2 adjacent labels,
 - we can solve this efficiently using dynamic programming.
 - (Similar to Viterbi decoding.)
- Learning can be done with SGD and a similar dynamic program.

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